

Three-phase asynchronous motors for low voltage with squirrel-cage rotor

with EU efficiency classification



we get things moving



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Note:

We make all efforts to better our products. Versions, technical data and figures could be changed therefore. They are always not binding before written confirmation by the supply factory.





Standards and regulation

The motors comply with the relevant standards and regulations, particularly with the following:

Title	DIN EN / DIN VDE	IEC
Rotating electrical machines, rating and performance	DIN EN 60034-1	IEC 34-1 IEC 85
Rotating electrical machines, methods for determining losses and efficiency	DIN EN 60034-2	IEC 34-2
Totally enclosed three-phase induction motors with squirrel-cage, type IM B3	DIN 42673	(IEC 72)
Totally enclosed three-phase induction motors with squirrel-cage, type IM B5, IM B35 and IM B14	DIN 42677	(IEC 72)
Rotating electrical machines, terminal markings and direction of rotation	DIN VDE 0530 p. 8	IEC 34-8
Rotating electrical machines, symbols for types of construction and mounting arrangements	DIN EN 60034-7	IEC 34-7
Rotating electrical machines, built-in thermal protection	-	IEC 34-11
Rotating electrical machines, methods of cooling	DIN EN 60034-6	IEC 34-6
Rotating electrical machines, classification of degrees of protection provided by enclosures	DIN EN 60034-5	IEC 34-5
Rotating electrical machines, mechanical vibrations of certain machines with shaft heights 56 mm and higher	DIN EN 60034-14	IEC 34-14
Cylindrical shaft ends for rotating electrical machines	DIN 748 p. 3	IEC 72
Rotating electrical machines, noise limits	DIN EN 60034-9	IEC 34-9
Rotating electrical machines, starting performance of single-speed three-phase cage induction motors for voltages up to 660 V, 50 Hz	DIN EN 60034-12	IEC 34-12
IEC standard voltages	DIN IEC 38	IEC 38

In addition, VEM motors comply with various foreign regulations which have been adapted to IEC 34-1

NF C 51	France
ÖVE M10	Austria
SS 426 0101	Sweden
SEV 3009	Switzerland
NBNC 51-101	Belgium
CEI 2-3, V1	Italy
NEK-IEC 34-1	Norway
BS 5000/BS 4999	Great Britain

and the Series K11R / K21R are also tested and available according to the regulations of the Classification Authorities

Germanischer Lloyd
Det Norske Veritas
American Bureau of Shipping
Russian Register
Lloyd's Register of Shipping
Bureau Veritas

With these standards and regulations, the following limits for temperature rise are valid:

Regulations	Temperature of cooling air °C	Permissible limits of temperature rise in K (measured by resistance method) Insulation class				
		A	E	B	F	H
DIN EN 60034-1/02.99	40	60	75	80	105	125
IEC 34-1	40	60	75	80	105	125
United Kingdom BS	40	60	75	80	105	125
Italy CEI	40	60	70	80	105	125
Sweden SEN	40	60	70	80	105	125
Norway NEK	40	60	-	80	105	125
Belgium NBN	40	60	75	80	105	125
France NF	40	60	75	80	105	125
Schweizerland SEV	40	60	75	80	105	125
Germanischer Lloyd	45	55	70	75	100	120
American Bureau of Shipping	50	50	65	70	90	115
Bureau Veritas	50	50	65	70	90	110
Norske Veritas	45	50	65	70	90	115
Lloyd's Register	45	50	65	70	95	110
Russian Register	40/45	60	75	85	110	125

The series K11R and K21R are tested at VDE Prüf- und Zertifizierungsinstitut Offenbach and certified with VDE's

EMC-label according to the certificate No. 94057 F.

Efficiency

The General Directorate Energy of the European Commission and CEMEP as an association of the European motor and drive manufacturers have, in a Voluntary Agreement, settled to classify three-phase low voltage asynchronous motors according to their efficiency. The Agreement includes all two-pole and four-pole standard motors in the output range between 1 and 100 kW, and the classification is done by labelling the motors with one of the three classes eff1, eff2, eff3, where eff3 is attached to motors with nowadays usual efficiencies, eff2 belongs to motors with significantly increased efficiencies, and eff1 is a mark for high-efficiency motors. In the Agreement is specified, to mark the motors on the nameplate with the respective class and to declare the respective classes for the motors in technical catalogues, moreover, in the catalogues must be specified data about efficiencies at partial loads. In the Agreement the DIN EN 60034-2 is expressly specified as the test procedure for determination of loss and efficiency. The mark for the efficiency classes is a Registered Trademark. VEM is among the subscribers of this Voluntary Agreement.

For the North American market, with respect to efficiency of three-phase low voltage motors the legal provisions of the so-called EAct (or EPCA = Energy Policy and Conservation Act) are in force, by them, depending on the pole-number, are also minimum efficiencies determined (Table 12.10 of NEMA MG1 or Tables 2 and 3 of CSA C390). The output range of the affected motors is between 1 and 500 hp in NEMA MG1, and between 1 and 200 hp in CSA C 390. When classifying European motors according to the American rules, attention must be paid to the fact that the test procedure for determination of loss and efficiency is expressly specified with the Standard IEEE 112, and that, when using this procedure for determination of efficiencies, the results will have significant deviations from those of DIN EN 60034-2, i.e. it results in considerably lower efficiencies. Motors of the VEM series WE1R are certified by CSA according to CSA C390.

Bearings / Bearing lubrication

VEM motors are equipped with bearings from excellent manufacturers. The bearings have a nominal service life of at least 20,000 hours for maximum permissible load conditions. Without additional axial loading for coupling service the nominal bearing service life is 40,000 hours.

The versions

- fixed bearing N-end
- without fixed bearing
- permanent lubrication
- relubrication device
- heavy bearing arrangement D-end (for increased lateral forces)
- easy bearing arrangement

and the

- bearing schedules
- disc spring and wave washer schedule
- V-rings
- figures of bearing arrangements
- flat grease nipples

are shown in the bearing arrangement tables. Fixed bearing D-end possible on request.

Any grooved ball bearings have disc springs and wave washers, respectively, thus they are preloaded. This is not true for versions with cylindrical roller bearings.

The version "fixed bearing N-end" is possible for motors "without fixed bearing".

Motors with permanent lubrication are also available with a degree of protection IP 56.

Motor sizes 56 – 160 are fitted with life-lubricated bearings. For motors from size 180, depending on the useful life of grease, bearings must be regreased in good time so that the scheduled bearing service life is reached. Under normal operating conditions, the grease packing will last for 10,000 hours of operation with 2pole version and for 20,000 hours of operation with versions from 4poles upwards without being renewed. For motors fitted with relubrication device and working under normal operating conditions, the grease will last for 2,000 hours of operation with 2pole version and 4,000 hours of operation with 4- and more-pole versions. The standard grease is a KE2R-40 type acc. to DIN 51825.

Use of cylindrical roller bearings

Using cylindrical roller bearings (heavy bearing arrangement), relatively high radial forces or masses can be accepted at the motor shaft end, e. g. belt drives, pinions or heavy-duty couplings.

The minimum radial force at the shaft end must be at least a quarter of the permissible one. Account must be taken of permissible shaft end loading. Both these values are found in the diagrams.

Important Note:

Radial forces below the minimum value can lead to bearing damage within a few hours. Test runs in no-load state are only permissible for a short period.

If the special minimum radial force cannot be met, we recommend the use of grooved ball bearings (easy bearing arrangement). Bearing change on request.

Vibration behaviour

The permissible vibration intensities of electric motors are specified in DIN EN 60034-14.

The vibration intensity stage N (normal) is achieved or bettered by VEM motors in the basic version. The vibration intensity

stages R (reduced) and S (special) are available at extra charge and depending on the type. Please consult the manufacturer.

According to DIN EN 60034-14 the following intensities are recommended:

Vibration intensity stages	Speed range rpm	Limit values of vibration velocity (mm/s) in frequency range 10 to 1000 Hz for sizes		
		80 – 112	132 – 200	225 – 400
N (normal)	600 – 3600	1.8	2.8	3.5
R (reduced)	600 – 1800 above 1800 – 3600	0.71 1.12	1.12 1.8	1.8 2.8
S (special)	600 – 1800 above 1800 – 3600	0.45 0.71	0.71 1.12	1.12 1.8

All rotors are dynamically balanced with the half key inserted. This balancing is documented on rating plate with the letter H

behind the motor number, balancing with full key on request. In that case, the code letter behind the motor number will be F.

Noise behaviour

Noise measurement is carried out according to DIN EN 23741/23742 at design output, design voltage and design frequency. In accordance with DIN EN 60034-9, the spatial mean value of the measurement area sound pressure level L_{pA} measured at a distance of 1 m from the machine outline is stated as noise intensity in dB (A).

The A-sound power level L_{WA} across the measurement area dimension L_S ($d = 1$ m) is also quoted with

$$L_{WA} = L_{pA} + L_S \text{ (dB)}$$

The measurement area dimensions are independent from the machine geometry and are for

size	L_S (dB)
63 - 132	12
160 - 225	13
250 - 315	14
355	15

The tabular value +4 dB (A) applies as an approximate value for motors in 60 Hz version. Binding data for 60 Hz are available on request.

The noise value for the basic types are quoted in tabular form. For special versions please refer to the manufacturer.

Ambient temperature

All VEM motors in the basic version can be used at ambient temperatures from -35 °C up to +40 °C.

Overload capacity

In compliance with DIN EN 60034-1, all motors can be exposed to the following overload conditions:

- 1.5 times the rated current for 2 min.
- 1.6 times the rated torque for 15 s (1.5 times for $I_A/I_N < 4.5$)

Both conditions apply to design voltage and design frequency.

Motor protection

The following motor protection versions are available as an option:

- motor protection with PTC thermistor sensors in the stator winding

- bimetallic temperature sensor as NC contact or NO contact in the stator winding
- resistance thermometer for monitoring the winding or bearing temperature on request

Tolerances – Electrical parameters

As specified by DIN EN 60034-1/02.99 the following tolerances are permissible:

Efficiency (indirect calculation)	- 0.15 (1- η) at $P_N \leq 50$ kW - 0.1 (1- η) at $P_N > 50$ kW
Power factor	$\frac{1-\cos\phi}{6}$ min. 0.02 max. 0.07
Slip (at rated load and operating temperature)	$\pm 20\%$ $P_N \geq 1$ kW $\pm 30\%$ $P_N < 1$ kW
Starting current (in the planned starting circuit)	+ 20 % no restriction downwards
Starting torque	- 15 % and + 25 %
Pull-up torque	- 15 %
Pull-out torque	- 10 % (with the application of this tolerance M_K/M at least 1.6)
Moment of inertia	$\pm 10\%$
Noise level (sound pressure level)	+ 3 dB (A)

These tolerances are permissible for the values assured for three-phase asynchronous motors, taking the necessary manufacturing tolerances and materials variations of the raw materials used into account. The standard contains the following notes on this:

1. A guarantee for all or any of the values shown in the table is not mandatory. In tender the guaranteed value for which permissible deviations should apply must be expressly

specified. The permissible variations must correspond to those stated in the table.

2. "Guarantee": In some countries, a distinction is drawn between guaranteed values and typical or declared values.

3. If a permissible deviation only applies in one direction, then the value in the other direction is not limited.

Tolerances – Mechanical parameters

Dimensional short sign acc. to DIN 42939	Meaning of dimensions	Fit or tolerance
a	Spacing of feet fixing holes in axial direction	± 1 mm
a ₁	Diameter or width across corners of attachment flange	± 1 mm
b	Spacing of feet fixing holes across axial direction	± 1 mm
b ₁	Diameter of flange spigot	up to diameter 230 mm j6 from diameter 250 mm h6
d, d ₁	Diameter of shaft end (cylindrical)	up to diameter 48 mm k6 from diameter 55 mm m6
e ₁	Pitch circle diameter of attachment flange	± 0.8 mm
f, g	Largest width of motor (without terminal box)	+ 2 %
h	Shaft height (lower edge foot to centre of shaft)	up to 250 mm -0,5 from 250 mm -1
k, k ₁	Overall length of motor	+ 1 %
l	$\leq \emptyset$ shaft end 55 mm $\geq \emptyset$ shaft end 60 mm	- 0.3 mm - 0.5 mm
p	Overall height (lower edge foot, housing or flange to highest point of motor)	+ 2 %
s, s ₁	Diameter of fixing holes of foot or flange	+ 3 %
t, t ₁	Lower edge of shaft end to upper edge key	+ 0.2 mm
u, u ₁	Width of key	h9
w ₁ , w ₂	Centre of first attachment hole to shaft end shoulder	± 3.0 mm
	Distance shaft shoulder – flange face, fix. bearing D-end	± 0.5 mm
	Distance shaft shoulder – flange face	± 3.0 mm
	Motor weight	- 5 up to +10 %



Three-phase motors with squirrel-cage rotor

with surface ventilation, mode of operation S1, continuous duty
insulation class F, degree of protection IP 55



Motor selection data with EU efficiency classification

Design point 400 V, 50 Hz

Type	P _B	n _B	EFF-	η _{4/4B}	η _{3/4B}	cos φ _B	I _B	I _A /I _B	M _A /M _B	M _S /M _B	M _K /M _B	J	m
	kW	rpm	-	%	%	-	400 V A	-	-	-	-	kgm ²	kg
Synchronous speed 3000 rpm – 2-pole version													
K21R 56 K2	0.09	2865		70.0	67.5	0.74	0.25	4.9	2.3	2.3	2.8	0.00013	4.4
K21R 56 G2	0.12	2830		70.3	69.6	0.77	0.32	4.5	2.1	2.1	2.3	0.00013	4.5
K21R 63 K2	0.18	2790		67.1	63.1	0.76	0.50	4.1	1.9	1.9	2.2	0.00013	4.9
K21R 63 G2	0.25	2800		68.1	65.6	0.72	0.74	4.2	2.2	2.2	2.4	0.00015	5.2
K21R 71 K2	0.37	2780		71.5	69.7	0.79	0.94	4.4	2.1	2.1	2.3	0.00025	6.7
K21R 71 G2	0.55	2815		74.3	72.7	0.81	1.38	5.1	2.3	2.1	2.6	0.00032	7.6
K21R 80 K2	0.75	2825		77.5	77.3	0.81	1.72	5.9	2.4	2.4	2.4	0.00057	10.7
K21R 80 G2	1.1	2835	2	77.8	77.4	0.80	2.55	6.0	2.4	2.3	2.6	0.00072	11.5
K21R 90 S2	1.5	2850	2	80.4	80.2	0.80	3.35	7.0	2.5	2.5	2.8	0.00132	16.0
K21R 90 L2	2.2	2850	2	82.0	81.5	0.85	4.55	7.5	2.8	2.3	2.9	0.0017	19.0
K21R 100 L2	3.0	2865	2	83.4	84.2	0.84	6.15	7.0	2.4	2.4	2.8	0.00275	25.0
K21R 112 M2	4.0	2900	2	84.4	84.7	0.81	8.4	7.0	2.2	2.1	2.9	0.0045	32
K21R 132 S2 T	5.5	2890	2	86.3	86.6	0.84	11	7.5	2.4	2.2	3.0	0.0055	40
K21R 132 SX2	7.5	2900	2	87.0	87.0	0.86	14.5	6.6	1.8	1.3	2.5	0.0110	57
K21R 160 M2	11.0	2900	2	88.5	88.5	0.90	20	7.0	2.4	2.0	3.0	0.0258	81
K21R 160 MX2	15.0	2930	2	89.4	89.4	0.90	27	7.1	2.2	1.7	2.9	0.0575	118
K21R 160 L2	18.5	2920	2	90.5	89.5	0.92	32	7.2	2.1	1.6	2.8	0.0675	134
K21R 180 M2	22	2935	2	91.8	91.0	0.92	37.5	6.8	1.7	1.4	2.6	0.105	165
K21R 200 L2	30	2940	2	92.8	92.0	0.92	50.5	7.3	2.0	1.6	2.9	0.128	195
K21R 200 LX2	37	2940	2	93.0	92.0	0.90	64	7.0	1.8	1.3	2.4	0.193	255
K21R 225 M2	45	2940	1	93.7	93.0	0.91	76	7.5	1.8	1.4	2.7	0.220	290
K21R 250 M2	55	2955	2	93.7	92.5	0.91	93	7.5	2.0	1.5	2.6	0.375	360
K21R 280 S2	75	2970	1	94.6	93.5	0.92	124	7.5	2.0	1.6	2.6	0.650	490
K21R 280 M2	90	2970	2	94.7	94.2	0.91	151	8.5	2.2	1.8	2.8	0.675	510
K21R 315 S2	110	2975		95.4	94.5	0.91	183	8.5	1.5	1.3	2.5	1.21	720
K21R 315 M2	132	2975		95.4	94.5	0.91	219	8.5	2.0	1.8	2.7	1.44	800
K21R 315 MX2	160	2975		96.0	95.0	0.93	259	8.5	2.0	1.6	2.6	1.76	980
K21R 315 MY2	200	2970		96.0	95.2	0.92	327	8.2	2.6	2.0	2.6	2.82	1170
K21R 315 L2	250	2973		96.1	95.2	0.93	404	7.3	2.1	1.4	2.0	3.66	1460
K21R 315 LX2	315	2975		96.7	95.5	0.92	511	7.4	2.4	1.4	2.0	4.43	1630
K22R 355 MY2	315	2988		96.8	96.6	0.88	534	8.6	1.3	1.0	3.0	4.10	1900
K22R 355 M2	355	2980		96.5	96.5	0.91	583	7.3	1.3	1.0	2.3	4.20	2000
K22R 355 MX2	400	2985		96.8	96.7	0.90	663	8.5	1.9	1.3	3.2	5.50	2200
K22R 355 LY2	450	2983		96.9	96.7	0.92	729	7.2	1.3	1.0	2.4	7.10	2400
K22R 355 L2	500	2985		97.2	97	0.92	807	8.2	1.8	0.9	2.6	7.10	2400

Three-phase motors with squirrel-cage rotor

with surface ventilation, mode of operation S1, continuous duty
insulation class F, degree of protection IP 55

Motor selection data with EU efficiency classification

Designpoint 400 V, 50 Hz

Type	P_B	n_B	EFF-	$\eta_{4/4B}$	$\eta_{3/4B}$	$\cos \varphi_B$	I_B	I_A/I_B	M_A/M_B	M_2/M_B	M_K/M_B	J	m
	kW	rpm	-	%	%	-	400 V A	-	-	-	-	kgm ²	kg
Synchronous speed 1500 rpm – 4-pole version													
K21R 56 K4	0.06	1410		60.5	56.8	0.60	0.24	3.1	2.3	2.3	2.7	0.00019	4.3
K21R 56 G4	0.09	1375		62.0	61	0.68	0.31	3.2	1.9	1.9	2.2	0.00019	4.4
K21R 63 K4	0.12	1370		57.5	56.7	0.68	0.44	3.2	1.9	1.8	2.2	0.00019	4.8
K21R 63 G4	0.18	1360		61.0	56.5	0.66	0.65	3.3	2.0	2.0	2.3	0.00024	5.2
K21R 71 K4	0.25	1385		64.6	62.3	0.72	0.78	3.6	1.8	1.8	2.1	0.00040	6.8
K21R 71 G4	0.37	1370		67.8	66.9	0.74	1.06	3.8	2.0	2.0	2.2	0.00050	7.8
K21R 80 K4	0.55	1400		71.5	69.3	0.69	1.60	4.1	2.1	2.0	2.3	0.00087	10.6
K21R 80 G4	0.75	1400		73.5	70.8	0.70	2.10	4.6	2.2	2.1	2.3	0.00107	11.7
K21R 90 S4	1.1	1410	2	76.6	75.3	0.79	2.62	5.5	2.3	2.2	2.5	0.00207	15.5
K21R 90 L4	1.5	1400	2	78.8	77.9	0.81	3.40	5.5	2.5	2.4	2.6	0.00260	18.0
K21R 100 L4	2.2	1410	2	81.0	80	0.76	5.15	6.0	3.0	2.7	3.1	0.00400	23.5
K21R 100 LX4	3.0	1430	2	82.6	82.3	0.79	6.70	6.5	2.3	2.1	2.8	0.00725	30
K21R 112 M4	4.0	1435	2	84.2	83.6	0.78	8.80	6.9	2.6	2.5	3.2	0.00900	37
K21R 132 S4 T	5.5	1425	2	85.7	85.3	0.77	11.8	6.3	2.5	2.4	2.9	0.01100	47
K21R 132 M4	7.5	1450	2	87.0	86	0.84	15	6.0	2.0	1.7	2.9	0.0280	70
K21R 160 M4	11.0	1450	2	88.4	88	0.85	21	6.8	2.2	1.9	3.3	0.0350	92
K21R 160 L4	15.0	1465	2	89.4	89	0.86	28	7.3	2.5	2.0	3.0	0.0780	120
K21R 180 M4	18.5	1460	2	90.0	89.5	0.86	34.5	6.8	2.5	2.0	2.9	0.0900	136
K21R 180 L4	22	1465	2	90.5	90.5	0.84	42	6.5	2.0	1.8	2.6	0.1380	170
K21R 200 L4	30	1465	2	91.5	91	0.85	55.5	7.0	2.0	1.7	2.4	0.1680	200
K21R 225 S4	37	1470	2	92.5	91.5	0.86	67	7.0	2.0	1.7	2.5	0.2750	270
K21R 225 M4	45	1470	2	93.0	92.5	0.86	81	7.0	2.0	1.7	2.5	0.3130	300
K21R 250 M4	55	1475	2	93.5	93	0.86	98.5	7.0	2.2	1.7	2.3	0.5250	375
K21R 280 S4	75	1480	2	94.1	93.5	0.86	134	7.0	2.0	1.7	2.2	0.9500	520
K21R 280 M4	90	1480	2	94.6	93.5	0.86	160	7.0	2.1	1.6	2.2	1.10	580
K21R 315 S4	110	1485		95.1	94.5	0.86	194	7.5	1.8	1.6	2.2	1.96	740
K21R 315 M4	132	1485		95.1	94.5	0.86	233	7.0	1.8	1.5	2.2	2.27	840
K21R 315 MX4	160	1480		95.0	94.8	0.87	279	7.0	1.8	1.5	2.0	2.73	1000
K21R 315 MY4	200	1485		96.0	95	0.88	342	7.5	2.0	1.8	2.4	4.82	1200
K21R 315 L4	250	1485		96.1	95	0.90	417	8.0	2.0	1.6	2.3	5.93	1510
K21R 315 LX4	315	1490		96.5	95.5	0.88	535	8.6	1.9	1.5	2.5	6.82	1630
K22R 355 MY4	315	1492		95.6	95.5	0.85	560	7.1	1.4	1.0	2.9	5.60	1950
K22R 355 M4	355	1490		96.8	96.5	0.84	630	8.1	1.8	1.0	3.1	7.9	2150
K22R 355 MX4	400	1494		96.8	96.7	0.84	710	8.6	1.3	1.0	3.0	9.5	2400
K22R 355 LY4	450	1490		96.8	96.7	0.82	818	8.0	1.2	1.0	3.0	10.0	2500
K22R 355 L4	500	1490		96.7	96.4	0.79	945	7.9	1.1	1.0	3.0	10.0	2500

Three-phase motors with squirrel-cage rotor

with surface ventilation, mode of operation S1, continuous duty
insulation class F, degree of protection IP 55

Motor selection data

Design point 400 V, 50 Hz

Type	P_B	n_B	EFF-	$\eta_{4/4B}$	$\eta_{3/4B}$	$\cos \varphi_B$	I_B	I_A/I_B	M_A/M_B	M_S/M_B	M_K/M_B	J	m
	kW	rpm	-	%	%	-	400 V A	-	-	-	-	kgm ²	kg
Synchronous speed 1000 rpm – 6-pole version													
K21R 63 K6	K20R 56 K6	0.09	895	50.5	45.3	0.56	0.46	2.5	2.0	2.0	2.4	0.00024	4.9
K21R 63 G6	K20R 56 G6	0.12	880	52.0	48	0.56	0.59	2.5	2.0	2.0	2.3	0.00027	5.7
K21R 71 K6	K20R 63 K6	0.18	925	58.0	54.5	0.51	0.88	2.8	1.6	1.6	2.1	0.00045	7.4
K21R 71 G6	K20R 63 G6	0.25	915	60.0	56.5	0.55	1.10	2.9	2.0	2.0	2.2	0.00060	8.3
K21R 80 K6	K20R 71 K6	0.37	915	66.0	62.5	0.66	1.22	3.4	2.0	2.0	2.0	0.00130	11.0
K21R 80 G6	K20R 71 G6	0.55	915	68.0	65.5	0.67	1.73	3.7	2.2	2.2	2.4	0.00175	12.5
K21R 90 S6	K20R 80 K6	0.75	935	70.0	67.5	0.64	2.43	4.5	2.4	2.4	2.4	0.00325	16.0
K21R 90 L6	K20R 80 G6	1.1	935	73.0	70	0.69	3.15	4.6	2.2	2.2	2.4	0.00425	19.0
K21R 100 L6	K20R 90 L6	1.5	945	76.4	76.2	0.73	3.90	4.6	2.1	2.0	2.4	0.00625	24.0
K21R 112 M6	K20R 100 L6	2.2	950	79.8	78.9	0.74	5.35	5.3	2.2	2.1	2.7	0.01225	33.5
K21R 132 S6	K20R 112 M6	3.0	955	78.5	78.5	0.82	6.7	5.7	1.8	1.6	2.7	0.0180	46
K21R 132 M6	K20R 112 MX6	4.0	955	80.0	79	0.80	9	6.0	2.2	2.0	3.1	0.0230	53
K21R 132 MX6	K20R 132 S6	5.5	955	83.0	83	0.83	11.5	5.0	1.8	1.5	2.3	0.0430	70
K21R 160 M6	K20R 132 M6	7.5	960	85.0	84	0.82	15.5	5.5	2.0	1.6	2.5	0.0530	86
K21R 160 L6	K20R 160 S6	11.0	965	85.2	85	0.86	21.5	5.0	2.0	1.7	2.3	0.1130	114
K21R 180 L6	K20R 160 M6	15.0	965	86.0	85	0.83	30.5	6.0	2.4	2.1	2.7	0.1450	136
K21R 200 L6	K20R 180 S6	18.5	970	88.1	88	0.87	35	5.5	2.0	1.7	2.4	0.2280	175
K21R 200 LX6	K20R 180 M6	22	970	88.8	88.5	0.87	41	6.2	2.2	1.8	2.6	0.2680	200
K21R 225 M6	K20R 200 M6	30	973	90.4	90	0.89	54	6.5	2.2	1.7	2.5	0.4430	265
K21R 250 M6	K20R 225 M6	37	975	91.0	90.8	0.89	66	6.5	2.2	1.7	2.3	0.8250	360
K21R 280 S6	K20R 250 S6	45	980	92.0	92	0.87	81	6.0	2.0	1.5	2.0	1.28	465
K21R 280 M6	K20R 250 M6	55	980	92.5	92	0.88	97.5	6.5	2.3	1.7	2.4	1.48	520
K21R 315 S6	K20R 280 S6	75	985	93.7	93	0.87	133	7.0	2.0	1.6	2.4	2.63	690
K21R 315 M6	K20R 280 M6	90	990	94.4	93.5	0.88	156	7.0	2.0	1.7	2.4	3.33	800
K21R 315 MX6	K20R 315 S6	110	990	94.0	93.8	0.88	192	7.5	2.2	1.7	2.6	3.60	880
K21R 315 MY6	K20R 315 M6	132	990	95.0	94.7	0.88	228	7.5	2.0	1.7	2.4	6.00	1050
K21R 315 L6	K20R 315 L6	160	985	95.3	95	0.89	272	7.5	2.3	1.9	2.4	6.67	1250
K21R 315 LX6	K20R 315 LX6	200	990	95.0	94.7	0.87	349	8.3	2.2	2.0	2.7	8.6	1460
K22R 355 MY6		200	995	96.1	96	0.83	362	7.0	1.5	1.3	2.4	8.1	1550
K22R 355 M6		250	994	96.0	95.7	0.81	464	7.0	1.8	1.3	2.3	8.2	1650
K22R 355 MX6		315	995	96.5	96.5	0.83	568	6.8	1.6	1.3	2.5	12.1	2200
K22R 355 LY6		355	995	96.0	95.8	0.78	684	7.4	1.9	1.4	2.6	14.0	2400

Three-phase motors with squirrel-cage rotor

with surface ventilation, mode of operation S1, continuous duty
insulation class F, degree of protection IP 55

Motor selection data

Design point 400 V, 50 Hz

Type	P_B	n_B	EFF-	$\eta_{4/4B}$	$\eta_{3/4B}$	$\cos \varphi_B$	I_B	I_A/I_B	M_A/M_B	M_S/M_B	M_K/M_B	J	m
	kW	rpm	-	%	%	-	400 V A	-	-	-	-	kgm ²	kg
Synchronous speed 750 rpm – 8-pole version													
K21R 71 K8	K20R 63 K8	0.09	675	45.5	40.3	0.51	0.56	2.1	1.9	1.9	2.1	0.00050	6.6
K21R 71 G8	K20R 63 G8	0.12	670	46.5	41.3	0.51	0.73	2.3	1.8	1.8	2.1	0.00060	8.1
K21R 80 K8	K20R 71 K8	0.18	690	56.5	53.8	0.59	0.78	2.8	2.0	2.0	2.2	0.00130	10.5
K21R 80 G8	K20R 71 G8	0.25	695	58.0	54	0.56	1.12	3.0	2.3	2.3	2.5	0.00175	12.0
K21R 90 S8	K20R 80 K8	0.37	700	61.5	56.3	0.54	1.6	3.0	1.9	1.9	2.1	0.00300	15.0
K21R 90 L8	K20R 80 G8	0.55	695	64.9	61.8	0.60	2.04	3.2	1.9	1.9	2.2	0.00375	18.0
K21R 100 L8	K20R 90 L8	0.75	705	67.0	64	0.60	2.7	3.3	2.0	2.0	2.3	0.00625	23.0
K21R 100 LX8	K20R 100 S8	1.1	705	73.0	72.5	0.67	3.25	4.0	2.0	2.0	2.4	0.00900	28.0
K21R 112 M8	K20R 100 L8	1.5	705	75.5	75.3	0.70	4.1	4.4	2.2	2.1	2.5	0.01225	33.5
K21R 132 S8	K20R 112 M8	2.2	705	75.5	75	0.76	5.5	4.5	1.7	1.6	2.3	0.01800	46
K21R 132 M8	K20R 112 MX8	3.0	705	78.0	78	0.75	7.4	4.5	1.7	1.6	2.3	0.0230	53
K21R 160 M8	K20R 132 S8	4.0	710	79.3	79	0.78	9.3	4.0	1.6	1.3	1.9	0.0430	70
K21R 160 MX8	K20R 132 M8	5.5	710	81.4	81	0.78	12.5	4.5	1.7	1.6	2.1	0.0530	86
K21R 160 L8	K20R 160 S8	7.5	725	83.0	83	0.78	16.5	4.5	1.8	1.6	2.1	0.1130	114
K21R 180 L8	K20R 160 M8	11.0	720	85.0	84	0.78	24	4.5	2.0	1.7	2.1	0.1450	136
K21R 200 L8	K20R 180 S8	15.0	725	86.5	86	0.79	31.5	5.0	2.0	1.7	2.3	0.228	175
	K20R 180 M8	18.5	725	87.5	86.5	0.80	38	5.0	1.9	1.7	2.2	0.268	200
K21R 225 S8		18.5	725	89.2	88	0.83	36	5.5	2.0	1.6	2.2	0.440	265
K21R 225 M8	K20R 200 M8	22	725	89.2	89	0.84	42.5	5.0	1.8	1.5	2.2	0.440	265
K21R 250 M8	K20R 225 M8	30	730	90.2	90	0.79	61	5.5	2.2	1.8	2.2	0.825	360
K21R 280 S8	K20R 250 S8	37	735	91.0	90.5	0.80	73.5	5.5	2.0	1.5	2.0	1.35	465
K21R 280 M8	K20R 250 M8	45	735	91.5	91	0.77	92	6.0	2.3	1.8	2.4	1.55	520
K21R 315 S8	K20R 280 S8	55	740	93.1	92	0.80	107	6.5	1.8	1.6	2.3	2.63	690
K21R 315 M8	K20R 280 M8	75	740	93.3	93	0.81	143	6.0	2.0	1.6	2.3	3.33	800
K21R 315 MX8	K20R 315 S8	90	740	93.5	93	0.81	172	6.0	1.9	1.6	2.2	3.60	880
K21R 315 MY8	K20R 315 M8	110	740	94.6	94	0.81	207	6.5	2.1	1.8	2.4	6.00	1100
K21R 315 L8	K20R 315 L8	132	740	95.0	94.3	0.83	242	6.3	2.0	1.7	2.1	6.76	1250
K21R 315 LX8	K20R 315 LX8	160	740	95.2	94.5	0.79	307	7.2	2.2	1.9	2.5	8.71	1430
K22R 355 MY8		160	744	95.2	95	0.80	303	6.8	1.3	1.0	2.5	9.3	1500
K22R 355 M8		200	743	95.6	95.3	0.77	392	6.5	1.6	1.0	2.7	9.5	1600
K22R 355 MX8		250	744	95.8	95.6	0.78	483	6.6	1.3	1.0	2.8	13.4	2200
K22R 355 LY8		280	744	95.3	95.1	0.78	544	8.2	1.2	1.0	2.8	15.8	2400

Noise data

Measurement area related sound pressure level L_{pA} for motors K21R, K22R in standard version

Design voltage and design output, 50 Hz

	L_{pA} dB	L_{pA} dB	L_{pA} dB	L_{pA} dB
	2pole	4pole	6pole	8pole
63 K	46	41	40	-
63 G	46	41	40	-
71 K	48	42	41	37
71 G	48	42	41	37
80 K	52	44	41	40
80 G	52	44	41	40
90 S	56	49	43	42
90 L	56	49	43	42
100 L	59	50	49	47
100 LX	-	50	-	47
112 M	61	53	51	50
112 MX	61	-	-	-
132 S	65	58	54	52
132 SX	65	-	-	-
132 M	-	60	54	52
132 MX	-	-	56	-
160 M	66	60	56	57
160 MX	67	-	-	57
160 L	67	62	61	57
180 M	-	62	-	-
180 L	-	-	61	58
180 M	70	-	-	-
180 L	-	64	-	-
200 L	73	64	62	61
200 LX	73	-	62	-
225 S	-	66	-	59
225 M	74	66	63	59
250 M	74	68	63	63
280 S	75	69	65	61
280 M	75	69	65	61
315 S	78	72	68	65
315 M	78	72	68	65
315 MX	79	76	70	65
315 MY	79	76	68	66
315 L	79	76	68	66
315 LX	79	76	68	66
355 MY, M, MX ¹⁾	77 ²⁾	77	70	68
355 LY, L ¹⁾	77 ²⁾	77	70	68

Measurement area related sound pressure level L_{pA} for motors K20R in standard version

	L_{pA} dB	L_{pA} dB	L_{pA} dB	L_{pA} dB
	2pole	4pole	6pole	8pole
56 K	46	41	40	-
56 G	46	41	40	-
63 K	48	42	41	37
63G	48	42	41	37
71 K	52	44	41	40
71 G	52	44	41	40
80 K	56	49	43	42
80 G	56	49	43	42
90 L	59	50	49	47
100 S	61	50	-	47
100 L	61	53	51	50
100 LX	-	-	-	-
112 M	65	58	54	52
112 MX	-	-	54	52
132 S	66	60	56	57
132 M	66	60	56	57
160 S	67	62	61	57
160 M	67	62	61	58
180 S	70	64	62	61
180 M	73	64	62	61
200 M	73	66	63	59
200 L	74	66	-	-
225 M	74	68	63	63
250 S	75	69	65	61
250 M	75	69	65	61
280 S	78	72	68	65
280 M	78	72	68	65
315 S	79	76	70	65
315 M	79	76	68	66
315 L	79	76	68	66
315 LX	79	76	68	66

¹⁾ series K22R

²⁾ with axial fan, rotation-sense dependable fan

The data given in the table are valid for nominal output, nominal voltage, and 50 Hz with tolerances of +3 dB. Noise measurement according to DIN EN 21 680 p. 1

Bearing arrangement

Basic version

Design selection data

Type	D-end						N-end			Figure		Fixed bearing	
	Antifriction bearing	V-ring	γ-ring	Felt ring	Wave washer	Disc spring	Antifriction bearing	V-ring	Wave washer	Felt ring	DS		NS
											DS		NS
K21R 63	6201 2Z C3	-	-	11.5x19	-	-	6201 2Z C3	-	32	12x22	1	2	without
K21R 71	6202 2Z C3	-	-	14.5x21	-	-	6202 2Z C3	-	35	15x24	1	2	without
K21R 80	6204 2Z C3	-	-	19.5x26	-	-	6204 2Z C3	-	47	20x32	1	2	without
K21R 90	6205 2Z C3	-	-	24.5x35	-	-	6205 2Z C3	-	52	25x40	1	2	without
K21R 100	6206 2Z C3	-	-	29.2x40	-	-	6206 2Z C3	-	62	30x50	1	2	without
K21R 100 LX	6206 2Z C3	-	-	29.2x40	-	-	6206 2Z C3	-	62	30x50	1	2	without
K21R 112 M	6206 2Z C3	-	-	29.2x40	-	-	6206 2Z C3	-	62	30x50	1	2	without
K21R 132 S2,4 T	6208 2RS C3	-	-	39x60	-	-	6206 2Z C3	-	62	30x50	1	2	without
K21R 132 S, SX2,M6,8	6208 2RS C3	-	-	-	80	-	6207 2RS C3	-	-	-	3	5	without
K21R 132 M4,MX6	6308 2RS C3	-	-	-	90	-	6308 2RS C3	-	-	-	3	5	without
K21R 160 M,MX8	6309 2RS C3	-	-	-	100	-	6308 2RS C3	-	-	-	3	5	without
K21R 160 MX2, L	6310 2RS C3	-	-	-	110	-	6309 2RS C3	-	-	-	3	5	without
K21R 180 M4, L6, 8	6310 2RS C3	-	-	-	110	-	6309 2RS C3	-	-	-	3	5	without
K21R 180 M2, L4	6310 C3	50A	-	-	110	-	6310 C3	50A	-	-	6	8	N-end
K21R 200 L, LX6	6312 C3	60A	-	-	-	130	6310 C3	50A	-	-	6	8	N-end
K21R 200 LX2	6312 C3	60A	-	-	-	130	6312 C3	60A	-	-	6	8	N-end
K21R 225 M2	6312 C3	60A	-	-	-	130	6312 C3	60A	-	-	6	8	N-end
K21R 225 S4, 8, M4,6,8,	6313 C3	65A	-	-	-	140	6312 C3	60A	-	-	6	8	N-end
K21R 250 M2	6313 C3	65A	-	-	-	140	6313 C3	65A	-	-	6	8	N-end
K21R 250 M4,6,8	6314 C3	70A	-	-	-	150	6313 C3	65A	-	-	6	8	N-end
K21R 280 S2,M2	6314 C3	70A	-	-	-	150	6314 C3	70A	-	-	6	8	N-end
K21R 280 S4,6,8,M4,6,8	6316 C3	80A	-	-	-	170	6314 C3	70A	-	-	6	8	N-end
K21R 315 S2,M2	6316 C3	80A	-	-	-	170	6316 C3	80A	-	-	6	8	N-end
K21R 315 S4,6,8,M4,6,8	6317 C3	80A	-	-	-	180	6316 C3	80A	-	-	6	8	N-end
K21R 315 MX2	6317 C3	-	RB85	-	-	180	6316 C3	80A	-	-	13	16	N-end
K21R 315 MX4,6,8	6220 C3	-	RB100	-	-	180	6316 C3	80A	-	-	13	16	N-end
K21R 315 MY2	6317 C3	-	RB85	-	-	180	6317 C3 ¹⁾	85A	-	-	18	19	N-end
K21R 315 MY4,6,8	6320 C3	-	RB100	-	-	215	6317 C3 ¹⁾	85A	-	-	18	19	N-end
K21R 315 L2, LX2	6317 C3	-	RB85	-	-	180	6317 C3 ¹⁾	85A	-	-	18	19	N-end
K21R 315 L4,6,8, LX4,6,8	6320 C3	-	RB100	-	-	215	6317 C3 ¹⁾	85A	-	-	18	19	N-end
K22R 355 MY/M/MX/LY/L 2pole	6317 C3	-	RB85	-	-	180	6317 C3 ¹⁾	85A	-	-	18	19	N-end
K22R 355 MY/M/MX/LY/L 4,6,8pole	6324 C3	120S	-	-	-	260	6317 C3 ¹⁾	85A	-	-	18	19	N-end

1) for vertical types of mounting Q317 C3
From size K21R 315 MX standard version with relubrication device

Type	D-end						N-end			Figure		Fixed bearing	
	Antifriction bearing	V-ring	γ-ring	Felt ring	Wave washer	Disc spring	Antifriction bearing	V-ring	Wave washer	Felt ring	DS		NS
											DS		NS
K20R 56	6201 2Z C3	-	-	11.5x19	-	-	6201 2Z C3	-	32	12x22	1	2	without
K20R 63	6202 2Z C3	-	-	14.5x21	-	-	6202 2Z C3	-	35	15x24	1	2	without
K20R 71	6204 2Z C3	-	-	19.5x26	-	-	6204 2Z C3	-	47	20x32	1	2	without
K20R 80	6205 2Z C3	-	-	24.2x35	-	-	6205 2Z C3	-	52	25x40	1	2	without
K20R 90	6205 2Z C3	-	-	24.5x35	-	-	6205 2Z C3	-	52	25x40	1	2	without
K20R 100	6206 2Z C3	-	-	29.2x40	-	-	6206 2Z C3	-	62	30x50	1	2	without
K20R 112 M2,4,6,8	6207 2RS C3	-	-	-	72	-	6207 2RS C3	-	-	-	3	5	without
K20R 112 MX6,8	6207 2RS C3	-	-	-	72	-	6207 2RS C3	-	-	-	3	5	without
K20R 132 S,M	6308 2RS C3	-	-	-	90	-	6308 2RS C3	-	-	-	3	5	without
K20R 160 S,M	6310 2RS C3	-	-	-	110	-	6309 2RS C3	-	-	-	3	5	without
K20R 180 S2,M2	6310 C3	50A	-	-	110	-	6310 C3	50A	-	-	6	8	N-end
K20R 180 S4,6,8 ; M4,6,8	6312 C3	60A	-	-	-	130	6310 C3	50A	-	-	6	8	N-end
K20R 200 M2,L2	6312 C3	60A	-	-	-	130	6312 C3	60A	-	-	6	8	N-end
K20R 200 M4,6,8 ; L4,6,8	6313 C3	65A	-	-	-	140	6312 C3	60A	-	-	6	8	N-end
K20R 225 M2	6313 C3	65A	-	-	-	140	6313 C3	65A	-	-	6	8	N-end
K20R 225 M4,6,8	6314 C3	70A	-	-	-	150	6313 C3	65A	-	-	6	8	N-end
K20R 250 S2,M2	6314 C3	70A	-	-	-	150	6314 C3	70A	-	-	6	8	N-end
K20R 250 S4,6,8 ; M4,6,8	6316 C3	80A	-	-	-	170	6314 C3	70A	-	-	6	8	N-end
K20R 280 S2,M2	6316 C3	80A	-	-	-	170	6316 C3	80A	-	-	6	8	N-end
K20R 280 S4,6,8 ; M4,6,8	6317 C3	80A	-	-	-	180	6316 C3	80A	-	-	6	8	N-end
K20R 315 S2	6317 C3	-	RB85	-	-	180	6316 C3	80A	-	-	13	16	N-end
K20R 315 S4,6,8	6220 C3	-	RB100	-	-	180	6316 C3	80A	-	-	13	16	N-end
K20R 315 M2: L2	6317 C3	-	RB85	-	-	180	6317 C3 ¹⁾	85A	-	-	18	19	N-end
K20R 315 M4,6,8 ; L4,6,8	6320 C3	-	RB100	-	-	215	6317 C3 ¹⁾	85A	-	-	18	19	N-end

1) for vertical types of mounting Q317 C3
From size K20R 315 standard version with relubrication device

Bearing arrangement

Special version "heavy bearing arrangement" VL

Design selection data

Type	D-end			N-end			Figure		Fixed bearing
	Antifriction bearing	V-ring		Antifriction bearing	V-ring		DS	NS	
		V-ring	γ-ring		V-ring	γ-ring			
K21R 132	S, SX2,M6,8 VL	NU 208 E	40A	-	6207 RS C3	-	4	10	N-end
K21R 132	M4,MX6 VL	NU 308 E	40A	-	6308 RS C3	-	4	10	N-end
K21R 160	M, MX8 VL	NU 309 E	45A	-	6308 RS C3	-	4	10	N-end
K21R 160	MX2, L VL	NU 310 E	50A	-	6309 RS C3	-	7	10	N-end
K21R 180	M4, L6, 8 VL	NU 310 E	50A	-	6309 RS C3	-	7	10	N-end
K21R 180	M2, L4 VL	NU 310 E	50A	-	6310 C3	50A	7	9	N-end
K21R 200	L, LX6 VL	NU 312 E	60A	-	6310 C3	50A	7	9	N-end
K21R 200	LX2 VL	NU 312 E	60A	-	6312 C3	60A	7	9	N-end
K21R 225	M2 VL	NU 312 E	-	RB60	6312 C3	60A	7	9	N-end
K21R 225	S4, 8, M4,6,8 VL	NU 313 E	-	RB65	6312 C3	60A	7	9	N-end
K21R 250	M2 VL	NU 313 E	-	RB65	6313 C3	65A	7	9	N-end
K21R 250	M4,6,8 VL	NU 314 E	-	RB70	6313 C3	65A	7	9	N-end
K21R 280	S2,M2 VL	NU 314 E	-	RB70	6314 C3	70A	7	9	N-end
K21R 280	S4,6,8,M4,6,8 VL	NU 316 E	-	RB80	6314 C3	70A	7	9	N-end
K21R 315	S2,M2 VL	NU 316 E	-	RB80	6316 C3	80A	7	9	N-end
K21R 315	S4,6,8,M4,6,8 VL	NU 317 E	-	RB85	6316 C3	80A	7	9	N-end
K21R 315	MX2 VL	NU 317 E	-	RB85	6316 C3	80A	15	16	N-end
K21R 315	MX4,6,8 VL	NU 2220 E	-	RB100	6316 C3	80A	15	16	N-end
K21R 315	MY2 VL	NU 317 E	-	RB85	6317 C3 ¹⁾	85A	20	19	N-end
K21R 315	MY4,6,8 VL	NU 320 E	-	RB100	6317 C3 ¹⁾	85A	20	19	N-end
K21R 315	L2, LX2 VL	NU 317 E	-	RB85	6317 C3 ¹⁾	85A	20	19	N-end
K21R 315	L4,6,8, LX4,6,8 VL	NU 320 E	-	RB100	6317 C3 ¹⁾	85A	20	19	N-end
K22R 355	M/MX/L 2pole VL	NU 317 E	-	RB85	6317 C3 ¹⁾	85A	20	19	N-end
K22R 355	M/MX/L 4,6,8pole VL	NU 324 E	120S	-	6317 C3 ¹⁾	85A	20	19	N-end

1) for vertical types of mounting Q317 C3

From size K21R 315 MX standard version with relubrication device

Type	D-end			N-end			Figure		Fixed bearing
	Antifriction bearing	V-ring		Antifriction bearing	V-ring		DS	NS	
		V-ring	γ-ring		V-ring	γ-ring			
K20R 112	M2.4.6.8 VL	NU 207 E	40A	-	6207 RS C3	-	4	10	N-end
K20R 112	MX6.8 VL	NU 207 E	40A	-	6207 RS C3	-	4	10	N-end
K20R 132	S.M VL	NU 308 E	40A	-	6308 RS C3	-	4	10	N-end
K20R 160	S.M VL	NU 310 E	50A	-	6309 RS C3	-	7	10	N-end
K20R 180	S2.M2 VL	NU 310 E	50A	-	6310 C3	50A	7	9	N-end
K20R 180	S4.6.8; M4.6.8 VL	NU 312 E	60A	-	6310 C3	50A	7	9	N-end
K20R 200	M2.L2 VL	NU 312 E	-	RB60	6312 C3	60A	7	9	N-end
K20R 200	M4.6.8; L4.6.8 VL	NU 313 E	-	RB65	6312 C3	60A	7	9	N-end
K20R 225	M2 VL	NU 313 E	-	RB65	6313 C3	65A	7	9	N-end
K20R 225	M4.6.8 VL	NU 314 E	-	RB70	6313 C3	65A	7	9	N-end
K20R 250	S2.M2 VL	NU 314 E	-	RB70	6314 C3	70A	7	9	N-end
K20R 250	S4.6.8; M4.6.8 VL	NU 316 E	-	RB80	6314 C3	70A	7	9	N-end
K20R 280	S2.M2 VL	NU 316 E	-	RB80	6316 C3	80A	7	9	N-end
K20R 280	S4.6.8; M4.6.8 VL	NU 317 E	-	RB85	6316 C3	80A	7	9	N-end
K20R 315	S2 VL	NU 317 E	-	RB85	6316 C3	80A	15	16	N-end
K20R 315	S4.6.8 VL	NU 2220 E	-	RB100	6316 C3	80A	15	16	N-end
K20R 315	M2: L2 VL	NU 317 E	-	RB85	6317 C3 ¹⁾	85A	20	19	N-end
K20R 315	M4.6.8; L4.6.8 VL	NU 320 E	-	RB100	6317 C3 ¹⁾	85A	20	19	N-end

1) for vertical types of mounting Q317 C3

From size K20R 315 standard version with relubrication device

Bearing arrangement

Figures

Design selection data

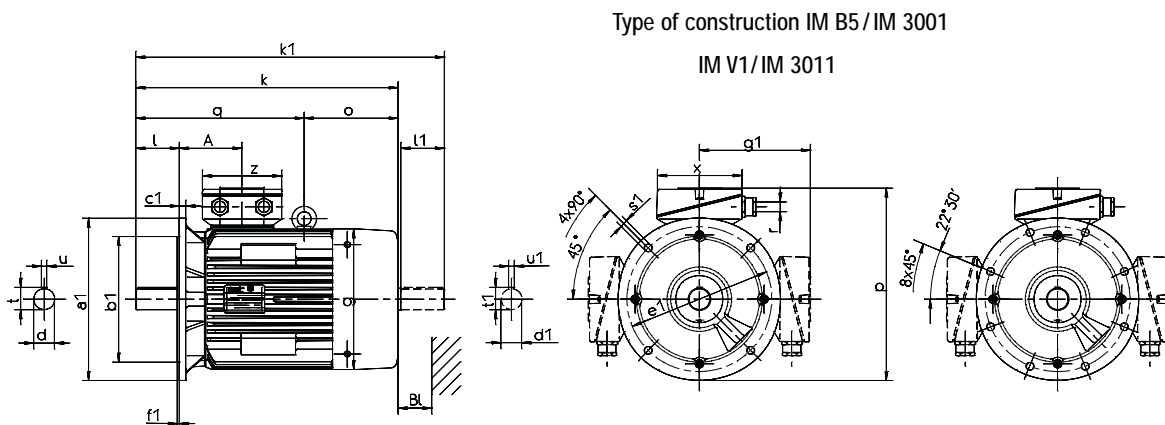
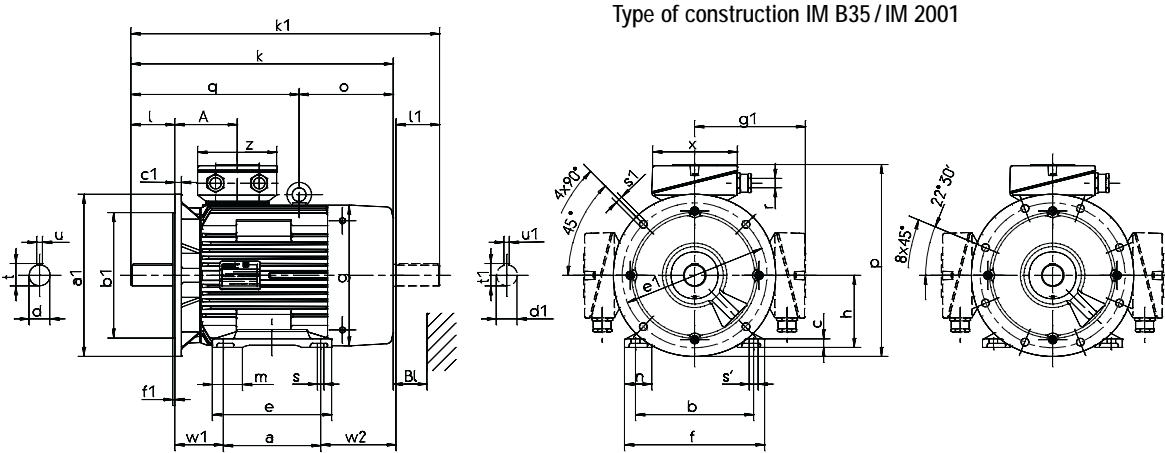
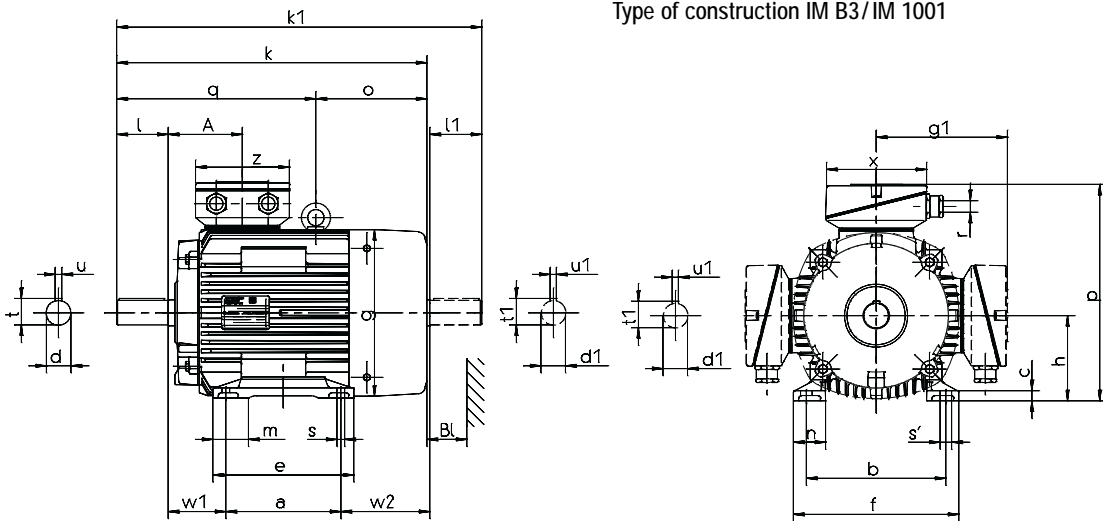
Fig.1	Fig. 2	Fig. 3	Fig.4
Fig.5	Fig. 6	Fig. 7	Fig. 8
Fig. 9	Fig. 10	Fig. 13	Fig. 15
Fig.16	Fig. 18	Fig. 19	Fig. 20

Three-phase motors with squirrel-cage rotor, basic version

with surface ventilation, cooling method IC 411, degree of protection IP 55

Design selection data

Dimensions



Three-phase motors with squirrel-cage rotor, basic version

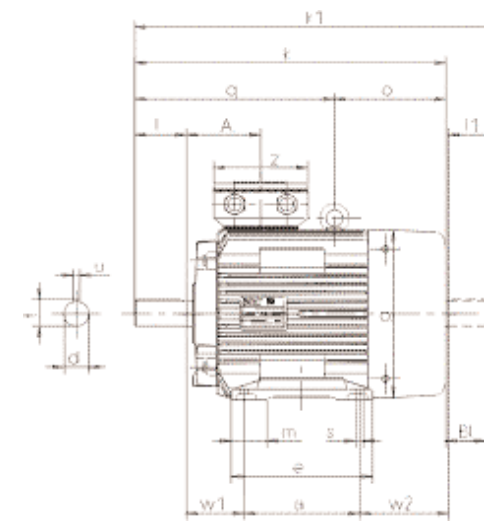
with surface ventilation, cooling method IC 411, degree of protection IP 55

Three-phase motors with squirrel-cage rotor, Transnorm version

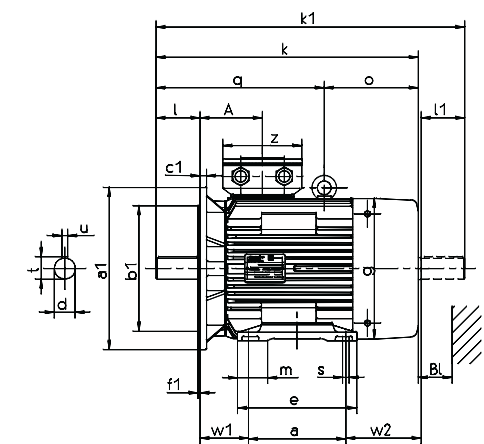
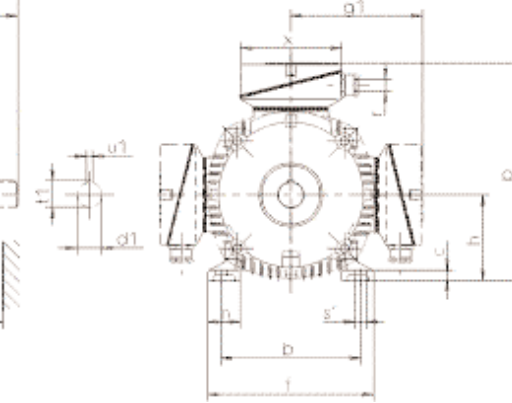
with surface ventilation, cooling method IC 411, degree of protection IP 55

Design selection data

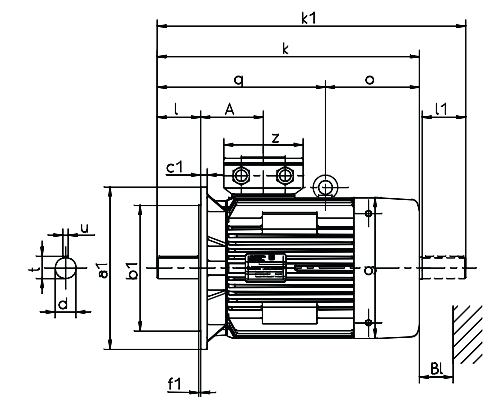
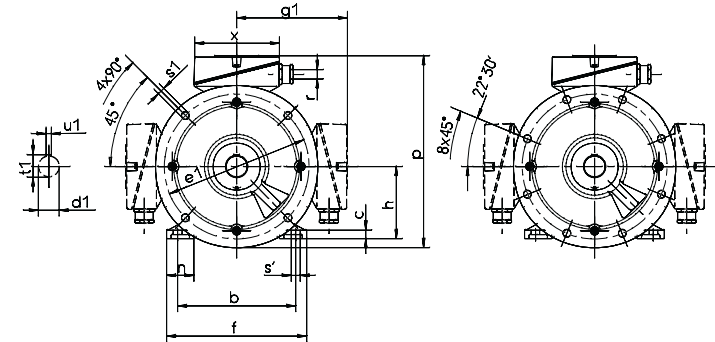
Dimensions



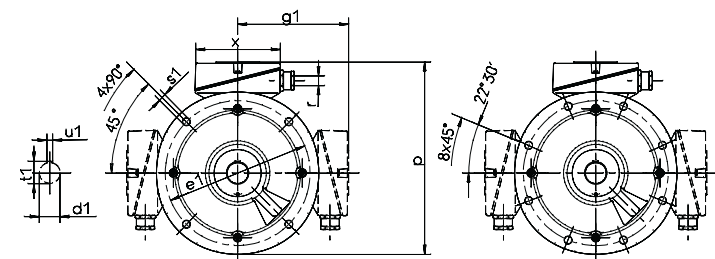
Type of construction IM B3/IM 1001



Type of construction IM B35/IM 2001



Type of construction IM B5/IM 3001
IM V1/IM 3011





Three-phase motors with squirrel-cage rotor, Transnorm version

with surface ventilation, cooling method IC 411, degree of protection IP 55



Paint finish

Normal finish

- adapted for group of climates 'moderate' acc. to IEC 721-2-1
Weather protected and non-weather protected locations, open-air-conditions, short-time up to 100 % relative air humidity at temperatures up to +30 °C, continuously up to 80 % relative air humidity up to +25 °C.

Finish system

Sizes 56 – 112

- all components except plastic parts (terminal box, fan cover) and aluminium terminal boxes: prime plastic paint, layer thickness $\geq 30 \mu\text{m}$
- finish coat water-soluble varnish with layer thickness $\geq 30 \mu\text{m}$
- special version 2K-varnish, layer thickness $\geq 30 \mu\text{m}$

Sizes 132 - 355

- prime coat plastic resin/zincphosphate, layer thickness $\geq 30 \mu\text{m}$
- finish coat 2K-(separate-application)-polyurethane varnish, layer thickness $\geq 30 \mu\text{m}$

Special finish

- adapted for group of climates 'world wide' acc. to IEC 721-2-1
Non-weather protected locations, open-air-conditions, in

aggressive atmospheres (chemical industries, sea environments) short-time up to 100 % relative air humidity at temperatures up to +35 °C, continuously up to 98 % relative air humidity at temperatures up to +30 °C.

Finish system

Size 56 – 112

- prime plastic paint, layer thickness $\geq 30 \mu\text{m}$
- finish coat 2K-varnish with layer thickness $\geq 60 \mu\text{m}$

Size 132 - 355

- prime coat plastic resin/zincphosphate, layer thickness $\geq 30 \mu\text{m}$
- second coat on separate application base, layer thickness $\geq 30 \mu\text{m}$
- finish coat 2K-(separate-application)-polyurethane varnish, layer thickness $\geq 30 \mu\text{m}$

Standard colour

RAL 7031 blue-grey

Additional special coating systems

- versions for excessive thermal stresses
- versions for excessive chemical and radiation stresses
- systems on customer's request

Pole-changing motors

Pole-changing motors are according to the load torque characteristics of driven machines designed for

- drives with a constant load torque and
- drives with a quadratically increasing load torque.

The intended application is stated in the motor selection data list. The motors can only be designed for one operating voltage, e.g. 230 V, 400 V or 660 V and are generally for direct connection via the pole sequence. 60 Hz version and special voltages according to IEC 38 are possible

Pole-changing is achieved by

- two separate windings in the stator, e. g. 6-4 poles
- one winding in a Dahlander circuit, e. g. 8-4 poles

- two separate windings, both in a Dahlander circuit, e. g. 12-8-6-4 poles

Whereas with the winding in a Dahlander circuit it is only possible to have a speed ratio of 1:2, two separate windings offer other speed variations, but with lower outputs in relation to the same basic version.

Y or Δ circuits are used for separate windings, Δ/YY or Y/YY for windings according to the Dahlander principle.

The following circuits are obtained with the individual variations in the number of poles:

Number of poles	Circuit	Basic version ²⁾
4-2, 4-2L	$\Delta/YY, Y/YY$	4pole ¹⁾
8-4, 12-6	Δ/YY	6pole
8-4L, LF	Y/YY	4pole
6-4	$Y/Y, \Delta/\Delta$	6pole
6-4LF, 6-4L	$Y/Y, \Delta/\Delta$	4pole
8-4-2	$Y/\Delta/YY$	6pole ¹⁾ up to K11R 160M
8-4-2	$Y/\Delta/YY$	4pole ¹⁾ up to K11R 160L
8-6-4	$\Delta/Y/YY$	6pole
12-8-6-4	$\Delta/\Delta/YY/YY$	6pole

¹⁾ From K21R 132, these motors have the 2pole ventilation system.

²⁾ not always for K21R 63–112

Star-circuit for the highest pole number (lowest speed) is possible, if the operation circuit is Δ . Other pole number combinations are also possible.

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Product overview

Three-phase standard motors

Sizes 56 – 355, IP 55

Squirrel-cage rotor, 0.12 – 500 kW

Slip-ring rotor, 2.2 – 250 kW

Base speeds: 3000, 1500, 1000, 750 rpm

Modifications

- foot-mounted types and flange mounting types
- pole-changing motors with 2, 3 and 4 speeds
- multi-voltage
- mounted star-delta switch
- explosion-protected type in the type of protection EEx e, EEx d and Ex nA
- motors for seagoing vessels
- designs for the dairying
- with forced-ventilation
- design with thermal winding protection
- increased degree of protection up to IP 65 S
- brake motors
- built-in motors 0.06 – 90 kW

Geared motor

- spur wheel back-geared motors
- conrate worm geared motors
- actuating geared motors

Three-phase asynchronous motors

From size 400, IP 55

low voltage design

squirrel-cage rotor and slip-ring rotor from 500 kW

in mechanical and electrical modifications

Single-phase asynchronous motors

Size 56 – 112

Squirrel-cage rotor, IP 55

with working capacitor 0.06 – 2.2 kW

Frequency converters and soft starters for three-phase asynchronous motors

- frequency converters for variable-speed three-phase drives 0.25 – 500 kW
- soft starters for variable-speed three-phase drives 0.75 – 500 kW

Three-phase special motors

- according to international classification rules for the shipbuilding up to 440 kW
- roller table motors up to 160 kW
- energy-optimized three-phase motors up to 315 kW
- motors for converter operation
- energy saving motors, 0.09 – 315 kW
- motors for fire gas and smoke exhausting fans 2.2 – 500 kW

Appliance motors

- Three-phase motors for special applications
- built-in motors, e.g. for refrigerating compressors

Three-phase asynchronous generators

- 2.2 – 420 kVA

Packaged drives

Size 80 – 180, in self-ventilated and forced-ventilated design with voltage/frequency control up to 7.5 kW field-oriented controlled 5.5 to 22 kW

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we get things moving

